Zirui Chen, Ph.D. Student

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https://czr-gif.github.io/



Education

2024 - Present Ph.D, Westlake University Intelligent Unmanned System Laboratory

Mentor: Prof. Shiyu Zhao

Tentative Thesis title: Data-Driven Control and Reinforcement Learning for Nonlinear

Robotic Systems

2021 – 2024 M.Eng., Beihang University, The Seventh Devision

Mentor: Prof. Zongyu Zuo

Thesis title: Nonsingular Guiding Vector Field for Geometric Path Following Control.

B.Eng., Beihang University, School of Automation Science and Electrical Engineering

Thesis title: Path Following Control for Airship.

Research Publications

Z. Chen, J. Tang, and Z. Zuo, "A novel prescribed-performance path-following problem for non-holonomic vehicles," en, *IEEE/CAA Journal of Automatica Sinica*, vol. 11, no. 6, pp. 1476–1484, Jun. 2024₀6. ODI: 10.1109/jas.2024.124311.

Z. Chen and Z. Zuo, "Non-singular cooperative guiding vector field under a homotopy equivalence transformation," en, *Automatica*, vol. 171, p. 111 962, Jan. 2025₀1. Ø DOI: 10.1016/j.automatica.2024.111962.

Skills

Programming Python, MATLAB/Simulink, LaTeX, Git.

Robotics & Control Nonlinear control design, model predictive control (MPC), reinforcement learning, optimal control, trajectory planning and tracking.

Languages Native in Mandarin Chinese; fluent in English (IELTS 6.5).

Miscellaneous Experience

Teaching Experience

Best Teaching Assistant Award, Beihang College, Beihang University.

Academic Service

Since 2024 Reviewer for Automatica, IEEE Transactions on Industrial Informatics (TII), and Journal of the Astronautical Sciences (JAS).